
Wideband and Broadband Digital Cross-Connect Systems Generic Criteria

Contents

1. Introduction.....	1-1
1.1 Purpose and Scope	1-1
1.2 Definitions and Nomenclature	1-1
1.3 Motivation	1-3
1.4 Generic Criteria.....	1-3
1.5 How To Use This Document.....	1-4
1.5.1 Document Structure and Organization.....	1-6
1.5.2 Related Documents	1-6
1.6 Revision History.....	1-8
2. Digital Cross-Connect Systems	2-1
2.1 Transport Interface Module.....	2-2
2.2 Operations Interface Module.....	2-3
2.3 Cross-Connect Matrix	2-3
2.4 Common Unit.....	2-4
2.5 Synchronization Module	2-5
2.6 Test-Access Module.....	2-5
3. DCS Applications	3-1
3.1 NE-Specific Applications.....	3-1
3.1.1 Grooming	3-1
3.1.2 Add/Drop	3-5
3.1.3 Facility Rolling	3-6
3.1.4 Broadcast of Digital Signals	3-10
3.2 Network Applications	3-10
3.2.1 Gateway Applications.....	3-11
3.2.1.1 DS _n -to-SONET Transport Gateway.....	3-11
3.2.1.2 Operations Gateway.....	3-13
3.2.2 Centralization of Operations Activities.....	3-15
3.2.3 Hubbing.....	3-15
3.2.4 Mesh.....	3-16
3.2.5 Ring Transport and Interconnection	3-16
3.3 Service Applications	3-19
3.3.1 Bandwidth Management Services.....	3-19
3.3.2 Network Restoration	3-19
3.3.2.1 DCS Hubbing Architecture.....	3-20
3.3.2.2 DCS Mesh Architecture.....	3-21

4.	Transport Criteria.....	4-1
4.1	Interfaces.....	4-1
4.1.1	DSn.....	4-1
4.1.2	SONET.....	4-2
4.2	Termination Functions.....	4-2
4.2.1	DSn Termination.....	4-2
4.2.1.1	DSn Line.....	4-2
4.2.1.2	DSn Path.....	4-3
4.2.2	SONET Termination.....	4-3
4.2.2.1	Section.....	4-3
4.2.2.2	Line.....	4-5
4.2.2.3	STS Path.....	4-5
4.2.2.4	VT Path.....	4-6
4.3	Cross-Connection.....	4-6
4.3.1	Unidirectional.....	4-7
4.3.2	Bidirectional.....	4-7
4.3.3	Broadcast.....	4-8
4.3.4	Loopback.....	4-9
4.3.4.1	DSn Loopback.....	4-11
4.3.4.2	VT Loopback.....	4-11
4.3.4.3	STS Loopback.....	4-11
4.3.5	Test Access.....	4-12
4.3.5.1	Monitor Test Access.....	4-12
4.3.5.2	Split Access.....	4-14
4.3.6	Cross-Connect Level.....	4-18
4.4	Payload Mappings.....	4-19
4.4.1	STS Level Mappings.....	4-19
4.4.2	Sub-STS-1 Level Mappings.....	4-19
4.5	Facility Rolling.....	4-19
4.6	Linear Automatic Protection Switching (APS).....	4-20
4.7	Unassigned Signal Codes.....	4-20
4.8	Bipolar Violation Transparency.....	4-20
5.	Synchronization Criteria.....	5-1
5.1	SONET DCS Synchronization.....	5-1
5.1.1	Timing Mode.....	5-1
5.1.2	Internal Clock.....	5-2
5.1.3	Timing Distribution.....	5-2
5.2	System Timing.....	5-2
5.3	Timing Transparency.....	5-3
6.	Operations Criteria.....	6-1
6.1	Operations Communications.....	6-1
6.1.1	Interfaces.....	6-1
6.1.2	Operations Communications Role.....	6-3

6.2	Memory Administration.....	6-4
6.2.1	Local and Remote Provisioning.....	6-5
6.2.2	Memory Backup.....	6-5
6.2.3	Remote Software Management.....	6-6
6.2.4	Security.....	6-7
6.3	Facility Maintenance.....	6-7
6.3.1	Detecting Defects in Transmission Signals.....	6-8
6.3.2	Applying Maintenance Signals.....	6-9
6.3.3	Indicating Transmission Failures.....	6-11
6.4	Frame Maintenance.....	6-11
6.5	Performance Monitoring.....	6-12
6.5.1	DSn Performance Monitoring.....	6-12
6.5.2	SONET Performance Monitoring.....	6-13
6.5.3	Enhanced Performance Monitoring.....	6-14
6.5.3.1	Enhanced SONET Optical Monitoring.....	6-14
6.5.3.2	Intermediate SONET Section Monitoring.....	6-14
6.5.3.3	Intermediate Path monitoring.....	6-15
6.6	Transmission Diagnostics.....	6-18
6.6.1	SONET Termination Diagnostics.....	6-18
6.6.2	Idle Signal Identification Diagnostic.....	6-18
6.6.3	Enhanced SONET Optical Diagnostic.....	6-19
6.6.4	Intermediate Path Trace Diagnostic.....	6-19
6.6.5	Path Trace Monitor Diagnostic.....	6-19
6.6.6	SONET Terminal Loopback Diagnostic.....	6-20
7.	System Performance Criteria.....	7-1
7.1	Cross-Connect Time.....	7-1
7.2	Transmission Delay.....	7-1
7.3	Jitter.....	7-2
7.3.1	Jitter Tolerance.....	7-3
7.3.2	Jitter Generation.....	7-4
7.3.3	Jitter Transfer.....	7-4
7.4	System Error Performance.....	7-4
8.	Systems Criteria.....	8-1
8.1	EDSX n/n.....	8-1
8.2	SONET EDSX.....	8-2
8.3	DCS 3/1.....	8-4
8.4	SONET W-DCS.....	8-6
8.5	SONET B-DCS.....	8-9
9.	Software Security.....	9-1
9.1	System Initialization Via a Disk Drive.....	9-1
9.2	Software Load Via a Tape Drive.....	9-1
9.3	Software Purity.....	9-2

10. Upgrade and Expansion Criteria	10-1
10.1 System Upgrade to SONET	10-1
10.2 System Expansion	10-2
10.3 Criteria for Hardware and Software Addition.....	10-2
10.4 Upgrade of Internal System Clock.....	10-2
10.5 Software Upgrade.....	10-3
10.6 Availability.....	10-3
10.6.1 Port Unavailability	10-3
10.6.2 Total System Unavailability.....	10-4
10.6.3 Control System Unavailability.....	10-4
11. Availability Criteria	11-1
12. Other Generic Criteria.....	12-1
Appendix A: Cross References.....	A-1
Appendix B: Deleted Criteria.....	B-1
Appendix C: DCS Criteria and Application Tables	C-1
References	References-1
Acronyms.....	Acronyms-1

List of Figures

Figure 1-1.	Digital Cross- Connect Systems	1-3
Figure 1-2.	How to Use this TR to identify the Criteria for a Type of DCS.	1-5
Figure 1-3.	Support-Document Tree for Cross-Connect Systems	1-7
Figure 2-1.	Digital Cross-Connect System Functional Block.....	2-2
Figure 3-1.	Example of Consolidation in a DCS.....	3-2
Figure 3-2.	Example of Segregation in a DCS	3-3
Figure 3-3.	Current Mode of Grooming	3-4
Figure 3-4.	Grooming using a W-DCS	3-5
Figure 3-5.	Example of the Steps involved in the Facility Rolling Application	3-7
Figure 3-6.	Digital Switch Cutover Using DCS 3/1.....	3-9
Figure 3-7.	Example of the Broadcast Application.....	3-10
Figure 3-8.	Examples of SONET DCSs as Transport Gateway NEs	3-12
Figure 3-9.	Examples of DCS as Communication Gateway NE and Intermediate NE	3-14
Figure 3-10.	Use of a DCS in the Hubbing Configuration.....	3-16
Figure 3-11.	Example of Ring Transport and Interconnection	3-18
Figure 3-12.	Network Restoration	3-21
Figure 4-1.	Unidirectional Cross-Connection	4-7
Figure 4-2.	Bidirectional Cross-Connection	4-7
Figure 4-3.	1:2 Broadcast Cross-Connection	4-9
Figure 4-4a.	Facility Loopback.....	4-10
Figure 4-4b.	Cross-Connect Loopback	4-10
Figure 4-4c.	Facility I/O Loopback.....	4-10
Figure 4-5.	Monitoring Test Access for the EDSX.....	4-13
Figure 4-6.	Monitoring Test Access for the DCS 3/1	4-13
Figure 4-7.	Monitoring Test Access for the W-DCS	4-14
Figure 4-8.	Monitoring Test Access for the B-DCS	4-14
Figure 4-9.	Series Split Access for the EDSX.....	4-15
Figure 4-10.	Series Split Access for the DCS 3/1	4-16
Figure 4-11.	Series Split Access for the W-DCS	4-16
Figure 4-12.	Series Split Access for the B-DCS	4-17
Figure 4-13.	Per-side Split Access	4-18
Figure 6-1.	“Near-End” and “Far-End” at Intermediate Path Monitor	6-17
Figure 7-1.	Example of Categories I and II for DCS Interfaces.....	7-3
Figure 8-1.	DCS 3/1	8-4
Figure 8-2.	SONET W-DCS	8-6
Figure 8-3.	SONET B-DCS.....	8-10

List of Tables

Table 2-1.	Types of Digital Cross-Connect System	2-1
Table 10-1.	DCSs Upgrade Path	10-1
Table C-1.	DCS Required Functions for Transport.....	C-1
Table C-2.	Operations Criteria for DCS	C-2
Table C-3.	Application for DCSs	C-3